

#### **Grubb Lease Post-Survey Field Operations and Compliance Report**

eTrac Inc. performed a hydrographic survey of Grubb Lease in the vicinity of Ventura, California on January 10<sup>th</sup> and 11<sup>th</sup> 2019. eTrac utilized an R2Sonic 2024 Multibeam Echosounder operating at 400Khz to collect bathymetry and backscatter imagery at the site. The purpose of the survey was to map bathymetry contours, locations of aquatic vegetation, and submerged pipeline structures inside the provided survey area. Survey vessel data collection track lines have been included in ASCII format and are attached with this report. The survey vessel track line data is also timestamped with times in UTC format.

Notable environmental hazards were avoiding kelp and operating a small vessel in shallow waters which included a surf zone. To mitigate for the hazardous sea state, the survey was scheduled during calm conditions.

The sea state at the time of survey, on January 10<sup>th</sup> and 11<sup>th</sup> were reported to be approximately 2-4 feet in the survey area. Clear Skies with winds 5-15mph.

No safety incidents were reported.

No marine mammals were observed.



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## **Hydrographic Survey Log**

## **Project Description**

<u>Date</u>	<u>Client</u>	<u>Project Name</u>
1/10/2019	L123	Grubb Lease
<u>File Name Structure</u>	<u>Client Contact</u> Dan Holmes	<u>Location</u> Ventura CA
<u>Survey Type</u> Multibeam	<u>Stage</u>	Reach/Area/Station
<u>Contract Number</u>		
Personnel  Hydrographer (1)  Greg Crenshaw	<u>Hydrographer (2)</u>	<u>Vessel Operator</u> Shaun Akins
Weather Condition	Wind Speed	Wind Direction
Clear	5-10 mph	
<u>Swell</u> 3-4 ft	<u><b>Chop</b></u> 1-2 ft	Sea State  Moderate (1.25-2.5 m)
Survey Vessel	<u>Vessel Used</u> Tikaani (24' Monohull)	
Fuel Level Full	Port Motor Hours	Port Motor Oil Level Full
	Starboard Motor Hours	Starboard Motor Oil Level Full
<u>Geodesy</u>		
Horizontal Datum NAD_83	Vertical Datum MLLW	Map Projection  CA SPCS Zone 5 (0405)
<u>Units</u> U.S. Survey Feet	Height Correction Method Geoid12b	



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# **On-Board Positioning and Motion Systems**

<b>Primary Horizontal Position</b>	<b>Primary Vertical Position</b>	Motion System
POS MV V5 WaveMaster	POS MV V5 WaveMaster	POS MV V5 WaveMaster
<u>Update Rate</u>	<u>Update Rate</u>	<u>Update Rate</u>
<u>Sonar</u>		
<u>Sonar Unit</u>	Sonar Frequency	Ping Rate Limit
R2Sonic 2024	400 kHz (Object Detection Survey)	
Swath Width 120°	Absorbtion Setting (dB/km)	<u>Coverage</u>
<u>Software</u>		
Acquisition Software Qinsy v.8.1	Processing Software Qimera	Qinsy PPS (Network)



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## **Hydrographic Survey Log**

## **Project Description**

<u>Date</u>	<u>Client</u>	Project Name
1/11/2019	L123	Grubb Lease
File Name Structure	Client Contact  Dan Holmes	<u>Location</u> Ventura CA
<u>Survey Type</u> Multibeam	<u>Stage</u> Conditional Survey	Reach/Area/Station
<u>Personnel</u>		
<u>Hydrographer (1)</u> Greg Crenshaw	Hydrographer (2)	<u>Vessel Operator</u> Shaun Akins
Weather Conditions	<u>s</u>	_
<u>Sky</u> Clear	Wind Speed 5-10 mph	Wind Direction
<u>Swell</u> 3-4 ft	<u>Chop</u> 1-2 ft	<u>Sea State</u> Moderate (1.25-2.5 m)
Survey Vessel	<u>Vessel Used</u> Tikaani (24' Monohull)	
<u>Fuel Level</u> Full	Port Motor Hours	Port Motor Oil Level Full
	Starboard Motor Hours	Starboard Motor Oil Level Full
<u>Geodesy</u>		
Horizontal Datum NAD_83	Vertical Datum MLLW	Map Projection  CA SPCS Zone 5 (0405)
<u>Units</u> U.S. Survey Feet	Height Correction Method Geoid12b	



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<u>Sonar</u>		
Sonar Unit  R2Sonic 2024	Sonar Frequency 400 kHz (Object Detection Survey)	Ping Rate Limit
<u>Swath Width</u> 120°	Absorbtion Setting (dB/km)	<u>Coverage</u>
<u>Software</u>		
Acquisition Software Qinsy v.8.1	<u>Processing Software</u> Qimera	<u>Time Synch Method</u> Qinsy PPS (Network)

